

CONCEPT DRIFT

AN OVERVIEW

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SUPERVISED TRAINING – CLASSICAL APPROACH

- Get a set of labeled training data
 - The environment is static
 - The underlying distribution is assumed to be the same in the environment that the classifier will be employed
 - Generate a classifier using the training data
 - The training dataset is assumed to have all information necessary to learn the “concept”
 - Employ the classifier to label unknown instances
 - The classifier is representative in all environments
 - The classifier can be employed for an undefined period of time
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THE CONCEPT DRIFT PROBLEM

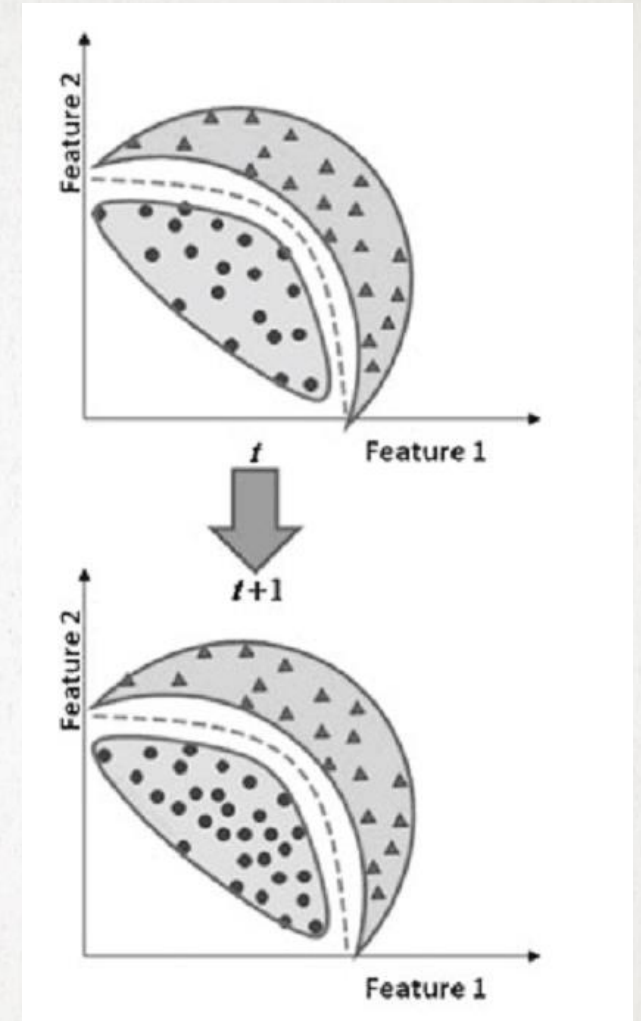
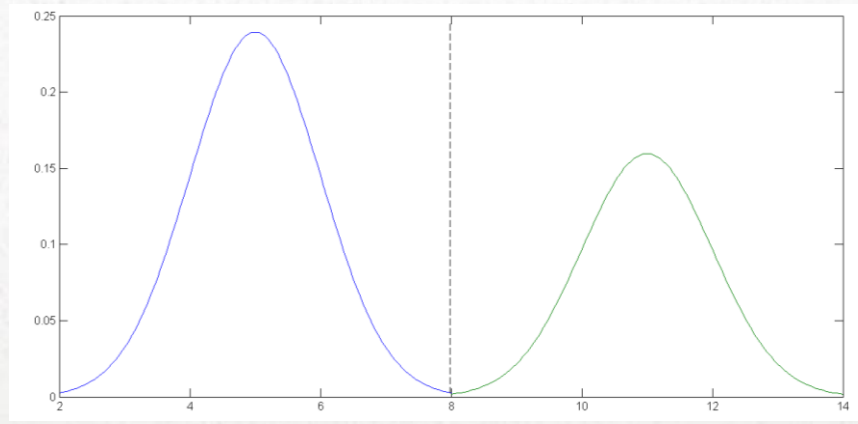
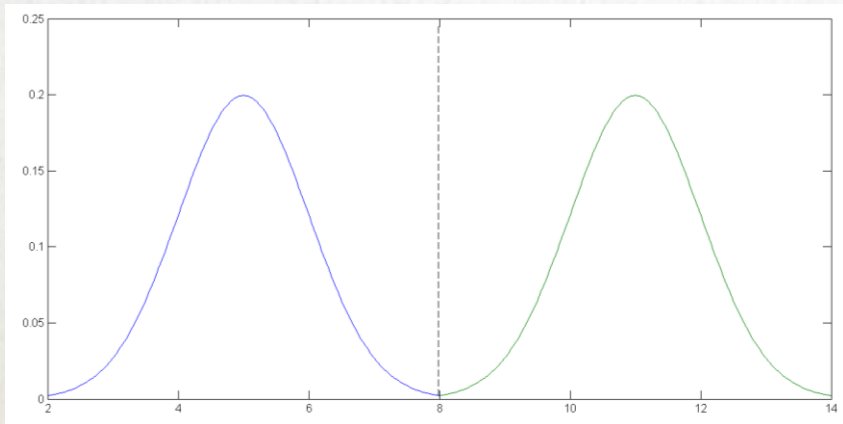
- The distributions stationarity is unrealistic for many real world problems
 - The problem evolves and changes over time, making the classifier obsolete
 - Examples: spam detection, fraud detection, climate analysis,...
- The boundaries generated by the classifier does not match with the current environment
 - A Concept Drift has occurred
 - Some measure need to be taken to adapt to the new concept
 - Retrain the classifier, train a new classifier

TYPES OF DRIFT

- Consider
 - A set of features x .
 - A target (class) variable y .
 - The a priori probabilities $P(x, y)$
 - The a posteriori probabilities $P(y, x)$

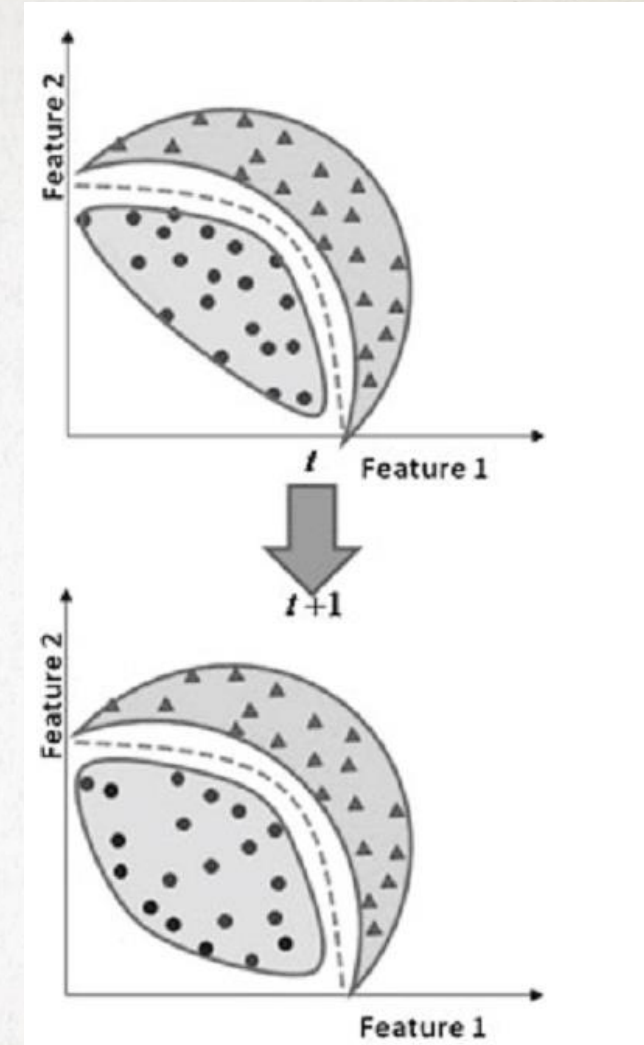
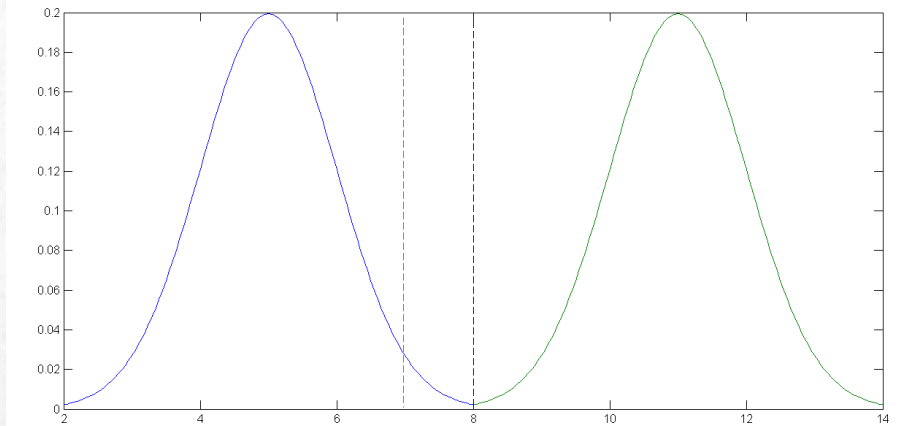
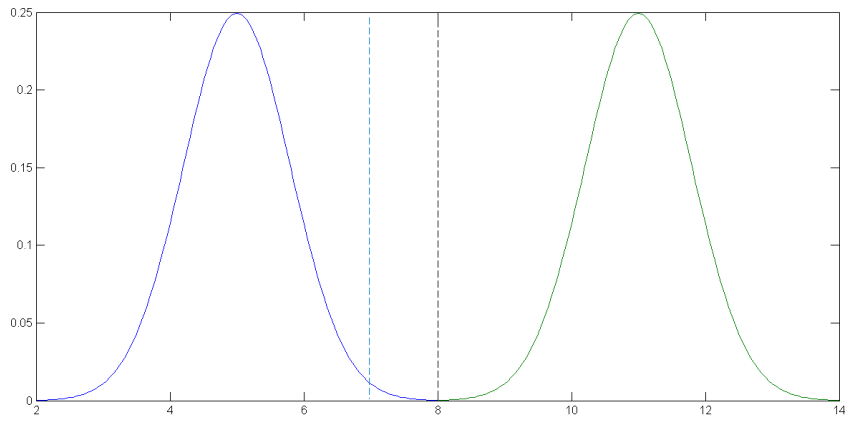
VIRTUAL DRIFT

- Also known as population drift
- Change in Class Priors
 - Change in the class distributions
 - $P_t(y) \neq P_{t+1}(y)$
 - Cost-sensitive learning



VIRTUAL DRIFT

- Change in the distribution
 - $P_t(y|x) = P_{t+1}(y|x)$
 - $P_t(x) \neq P_{t+1}(x)$
 - The boundary is “extended”, but still valid



VIRTUAL DRIFT – AN EXAMPLE

- Consider the problem of classifying parking spaces
 - Supervised training using images
- After training the classifier is employed
 - A virtual concept drift may happen if
 - The camera angle changes
 - The parking lot changes
 - Illumination changes



Training



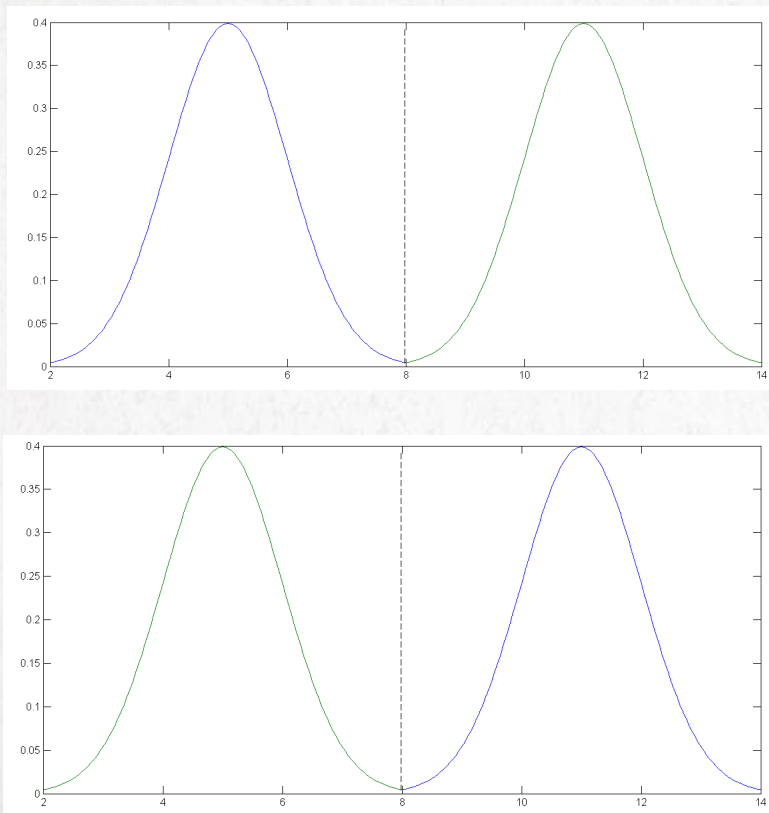
Testing

REAL CONCEPT DRIFT

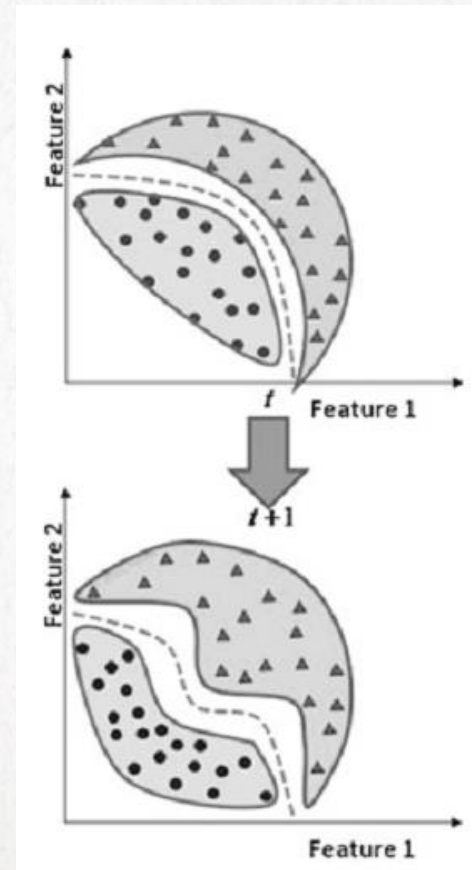
- The relationship between the feature vectors and the target class changes
 - $P_t(y|x) \neq P_{t+1}(y|x)$
 - The boundary's shape changes over time
 - Considered the most challenging drift
 - The classifier knowledge becomes irrelevant
 - The classifier could become a worse option than choosing at random

REAL CONCEPT DRIFT

Class swap



Gradual Drift



REAL CONCEPT DRIFT – AN EXAMPLE

- Consider the problem of classifying the user's e-mail
 - The e-mails would be classified as interesting or not for today
- The user's interests changes over time
 - The change is unpredictable
- Something that was interesting yesterday, is not today
 - Ex.: Yesterday the user was interested in the subject "computers", but today he is interested in "concept drift"

THE STABILITY PLASTICITY DILEMMA

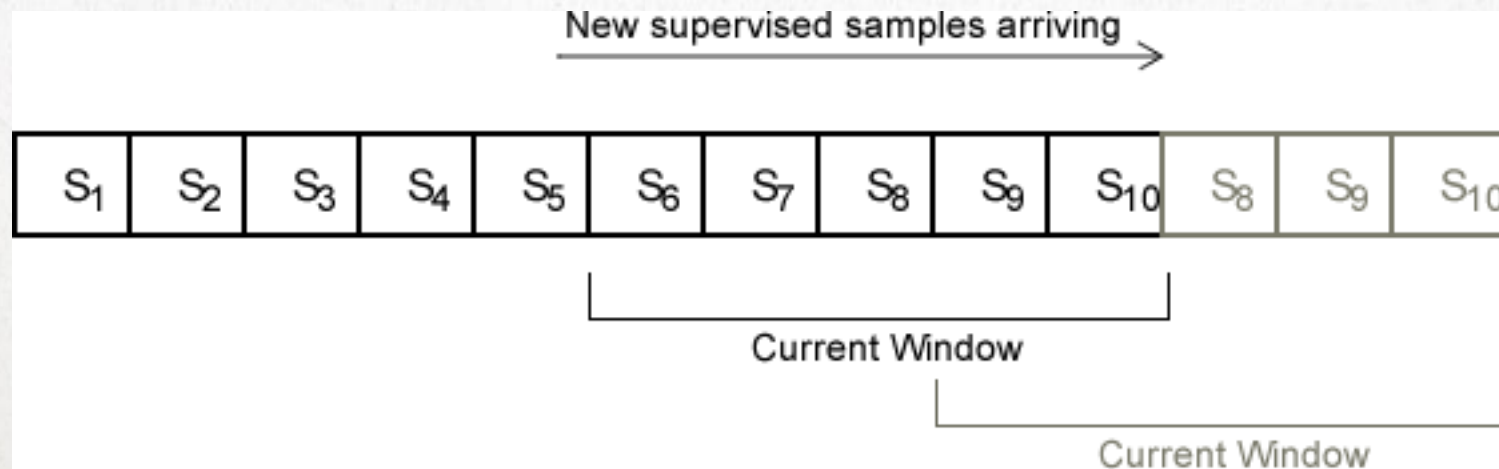
- How a learning system can be designed to be
 - Stable to irrelevant events (noise and outliers)
 - Able to learn new concepts (plasticity)
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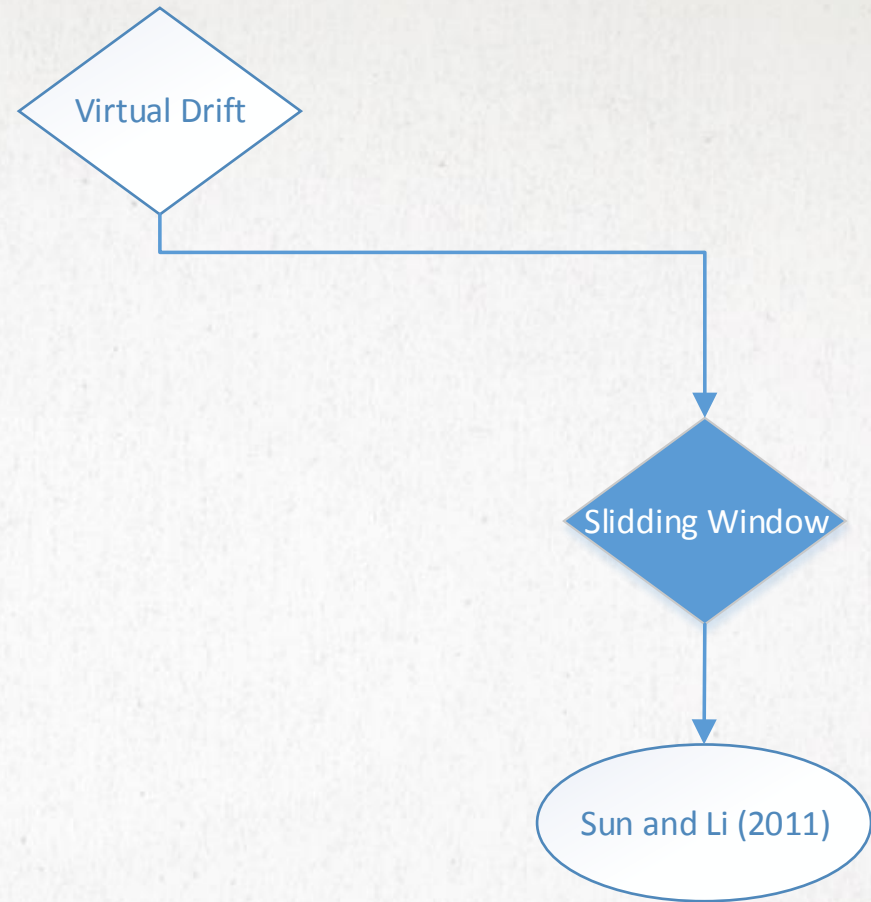
DEALING WITH CONCEPT DRIFT

- Authors considers that new supervised data will be available over time
 - Examples
 - The user will classify some e-mails when he changes his subject of interest (Just a few examples are available)
 - All real labels of the climate predictions for the next year will become available in the next year
 - Forms the new supervised data arrives
 - In a stream.
 - Ex.: A new supervised instance for every hour
 - In batches containing several supervised instances.
 - Ex.: 1.000 supervised instances at every new month
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DEALING WITH CONCEPT DRIFT

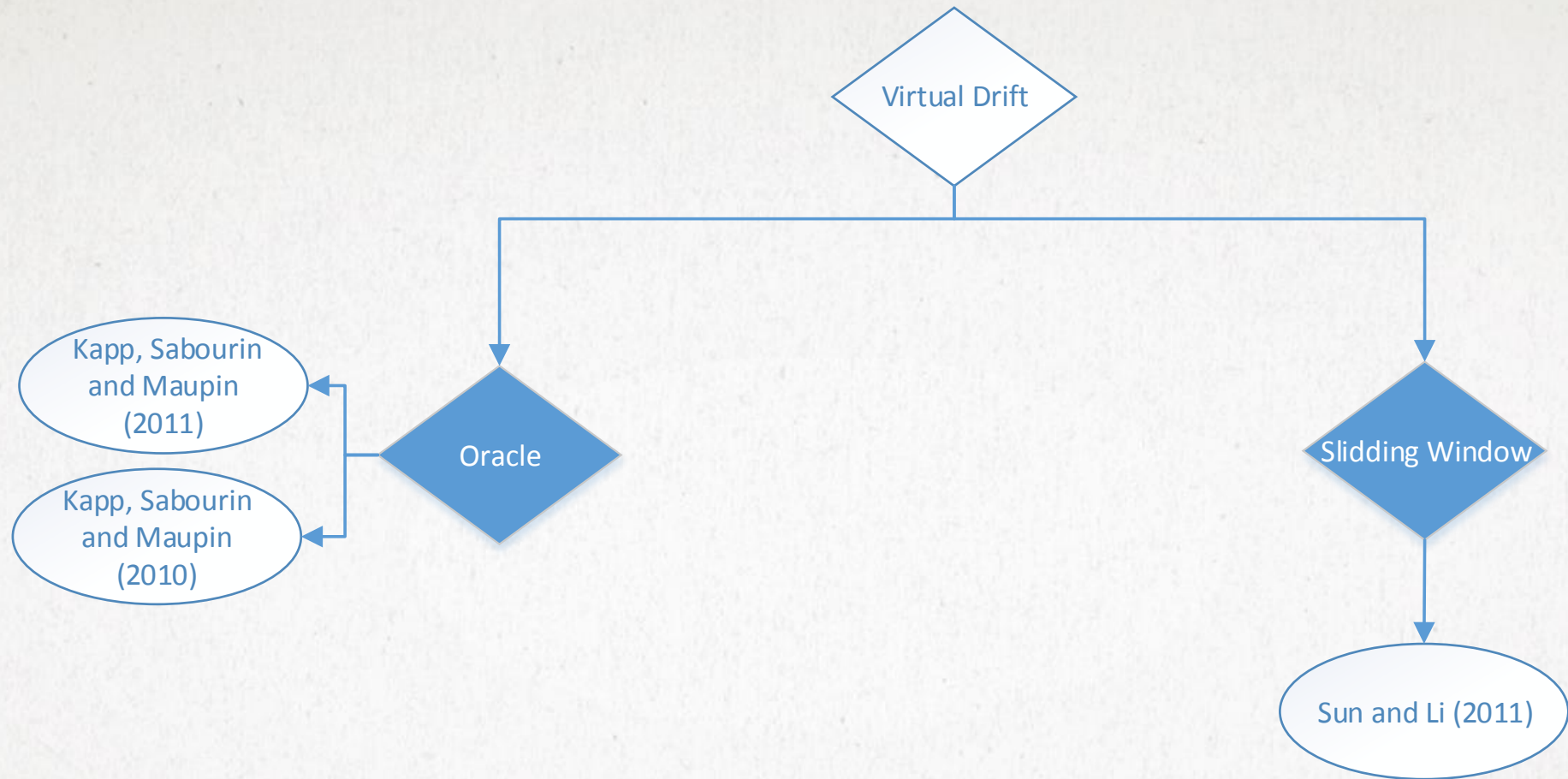
- Windowing
 - Passive method
 - Train the classifier using the N latest supervised instances
 - Greater values of N gives a better stability
 - Smaller values of N gives a better plasticity
 - How to define the window size?





DEALING WITH CONCEPT DRIFT

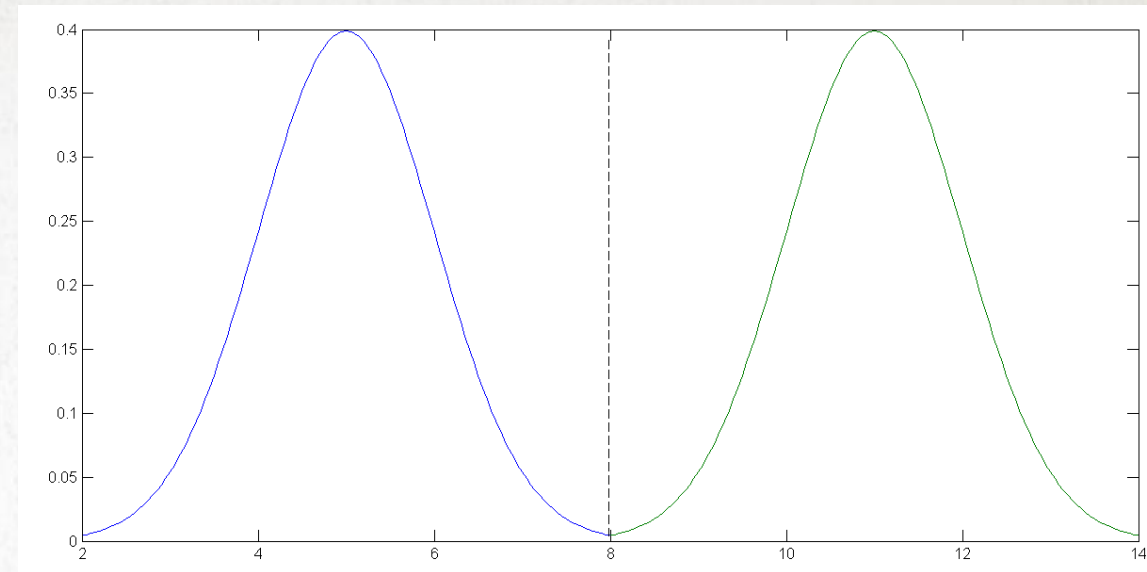
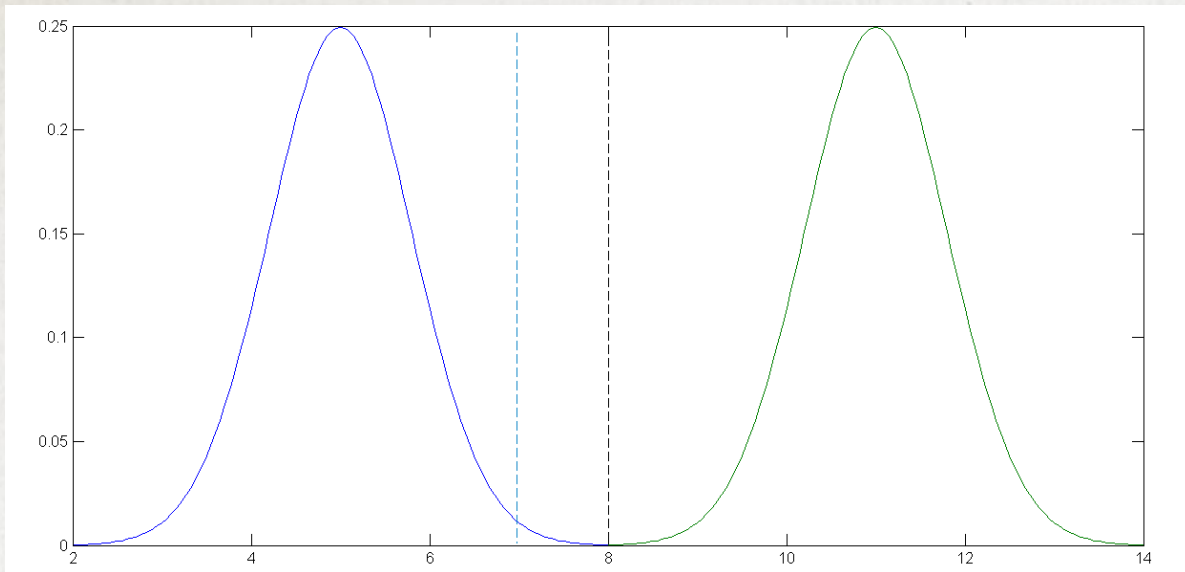
- Active Methods
 - Methods that actively tries to detect a drift and recover from it
 - Oracle
- False alarms versus undetected/delayed drifts



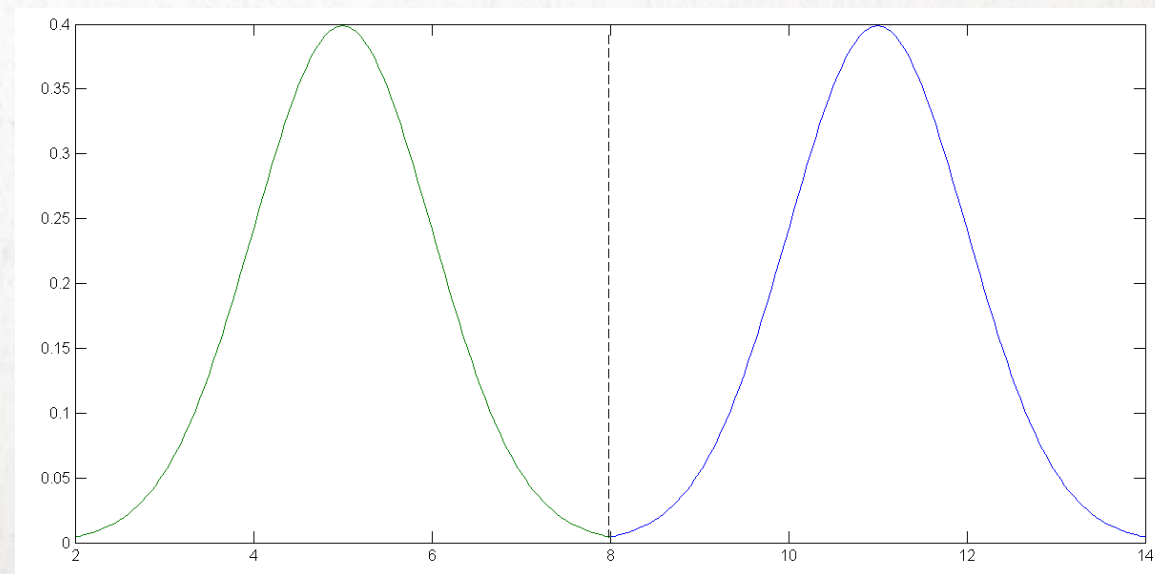
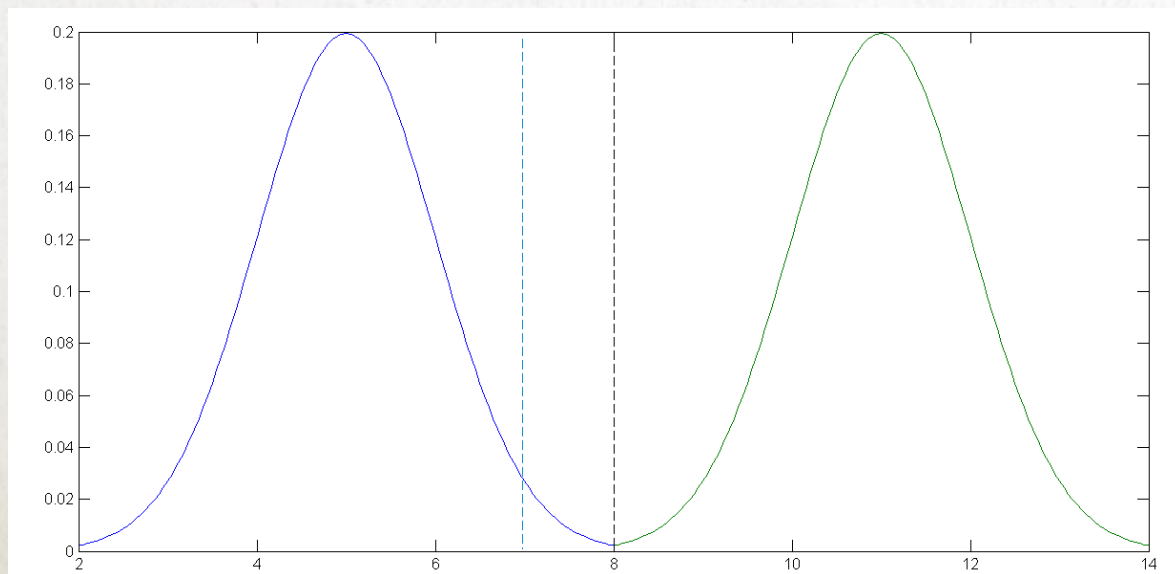
DEALING WITH CONCEPT DRIFT

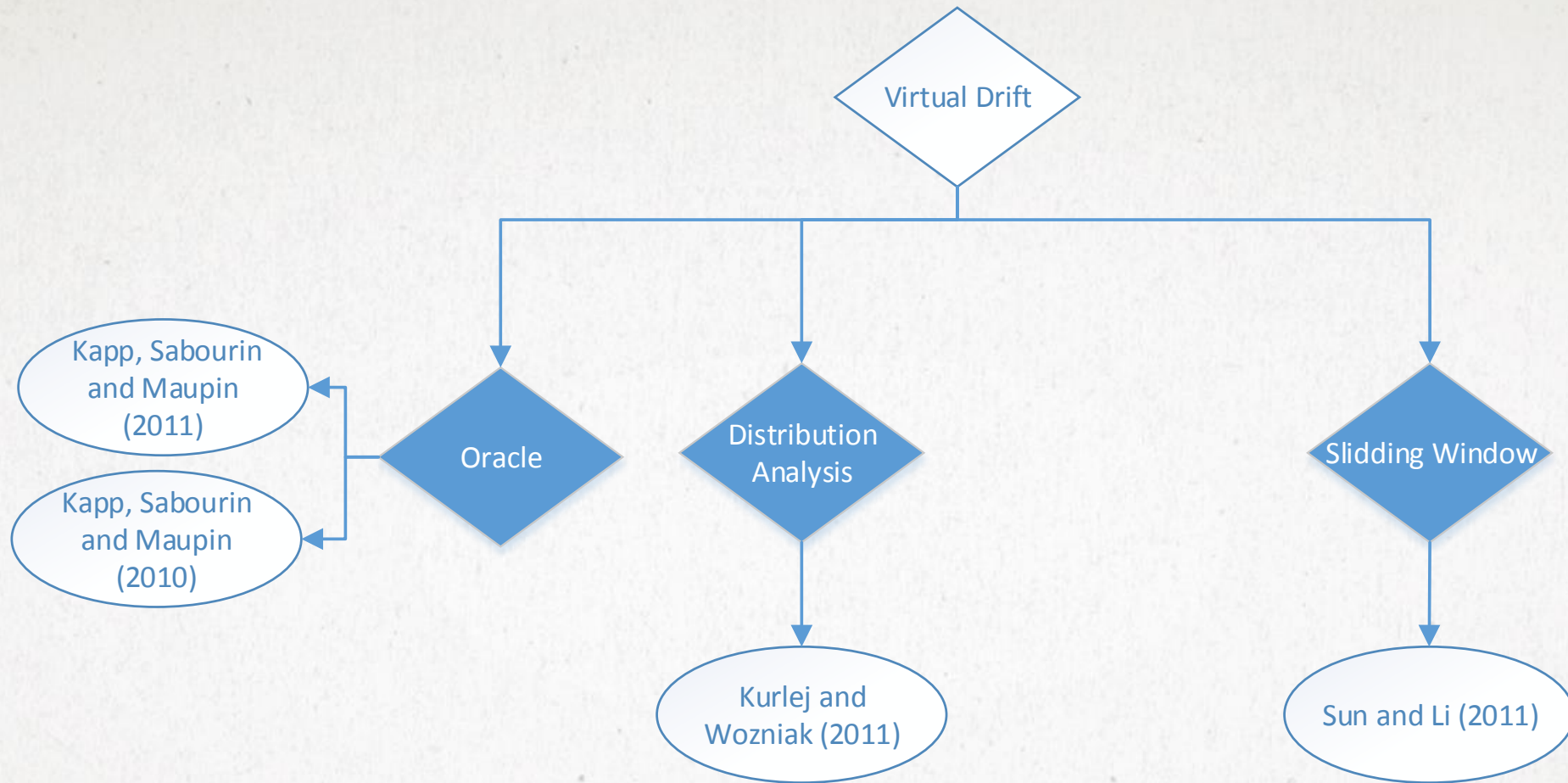
- Analyze the distribution of the new batch to detect drifts
 - Does not requires labeled instances
 - Labeled instances are required to build a new classifier if a drift is detected
- Some drifts may pass undetected using this technique
- Suitable for virtual drifts

Before the Drift



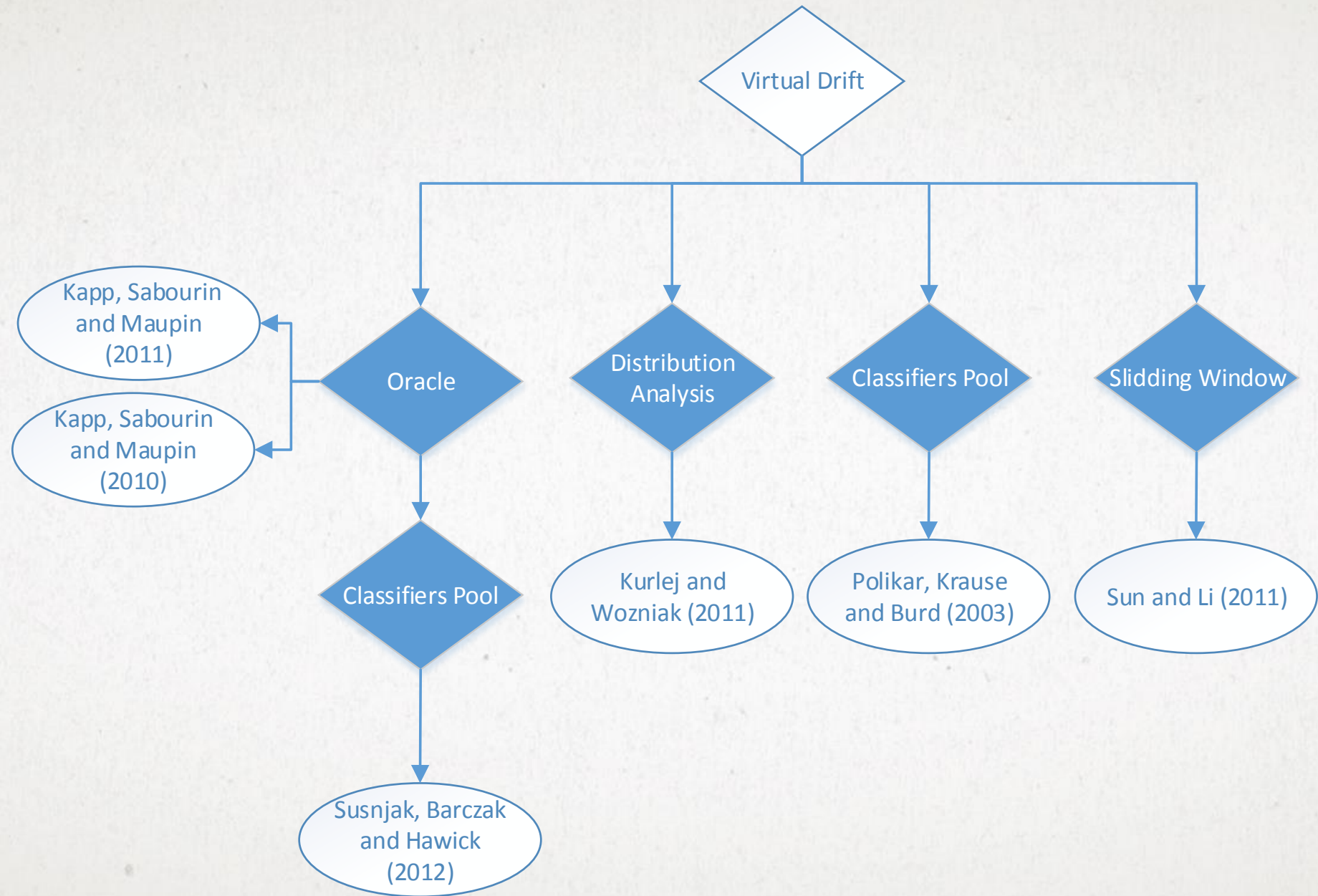
After the Drift

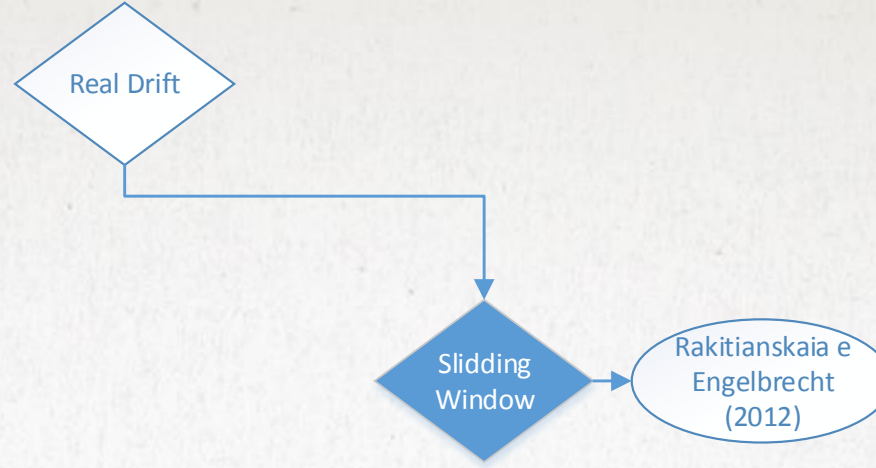


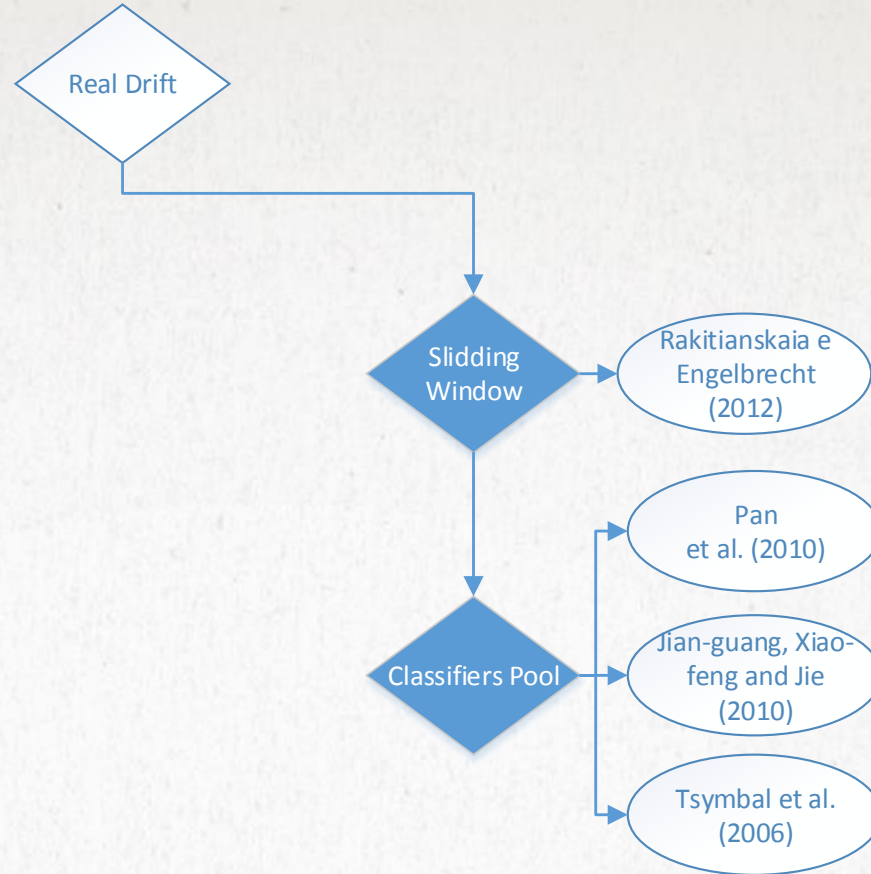


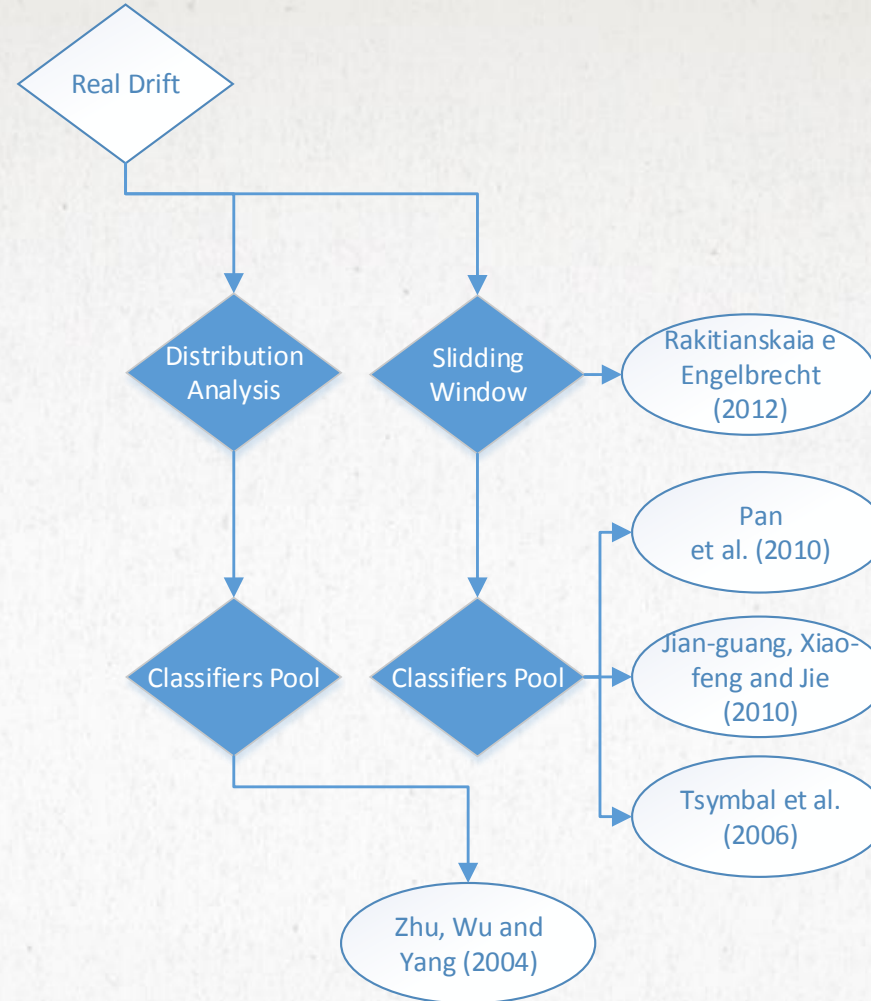
DEALING WITH CONCEPT DRIFT

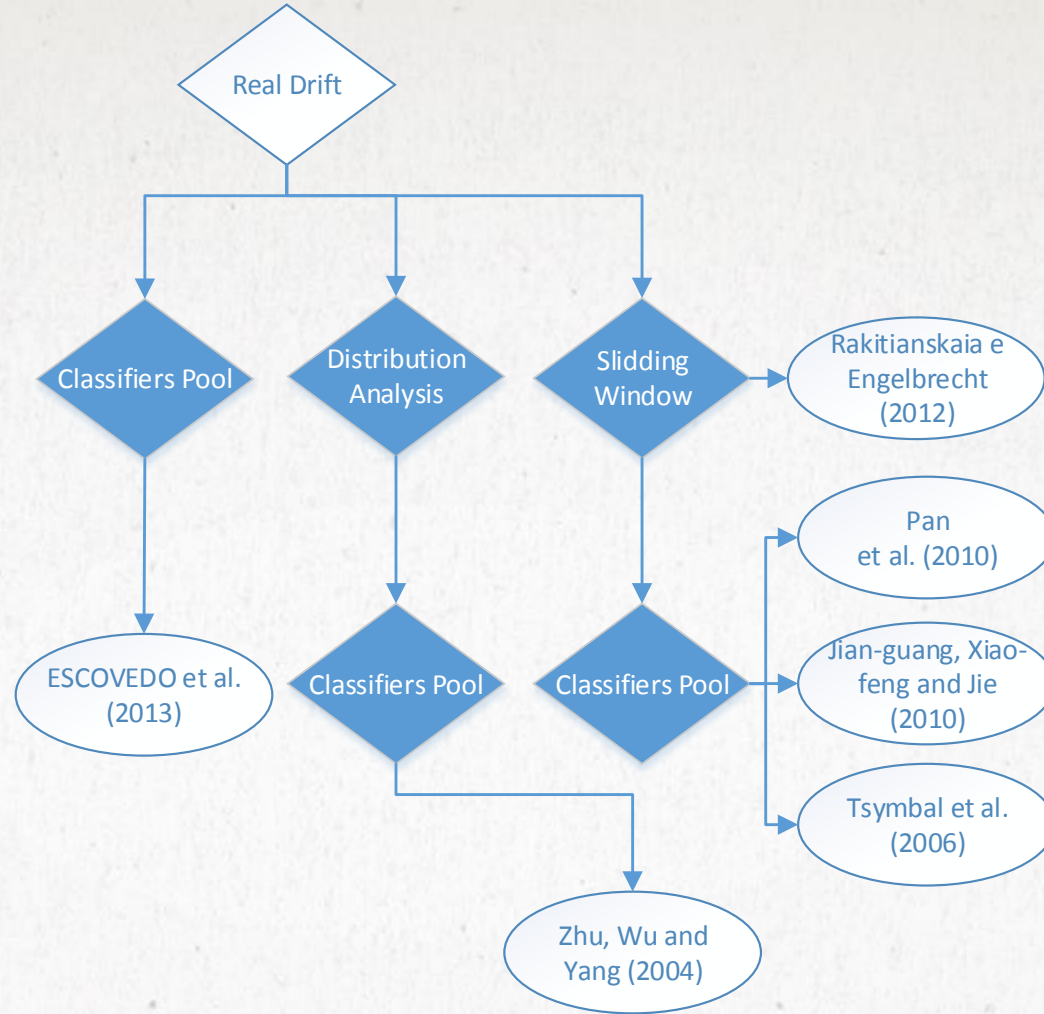
- Pool of Classifiers
 - Add a new classifier in the pool
 - Every time a drift is detected
 - For every new batch
 - Classifier weighting
 - Weights the classifier according to the performance in the latest batch
 - Pool management
 - Discard the worst performing classifiers
 - Discard classifiers with a performance below a threshold
 - Combining classifiers
 - Majority voting
 - Weighted majority voting
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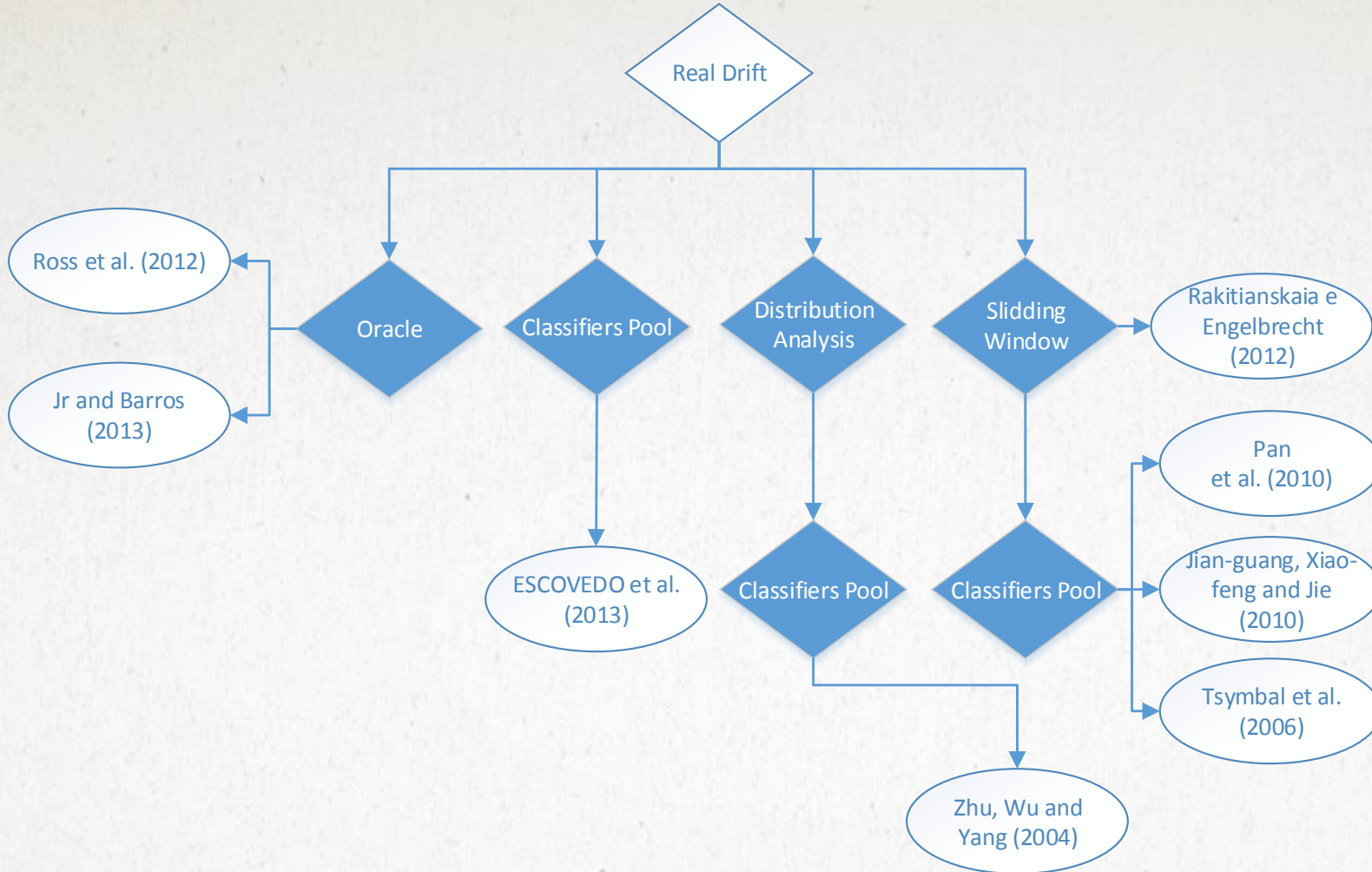


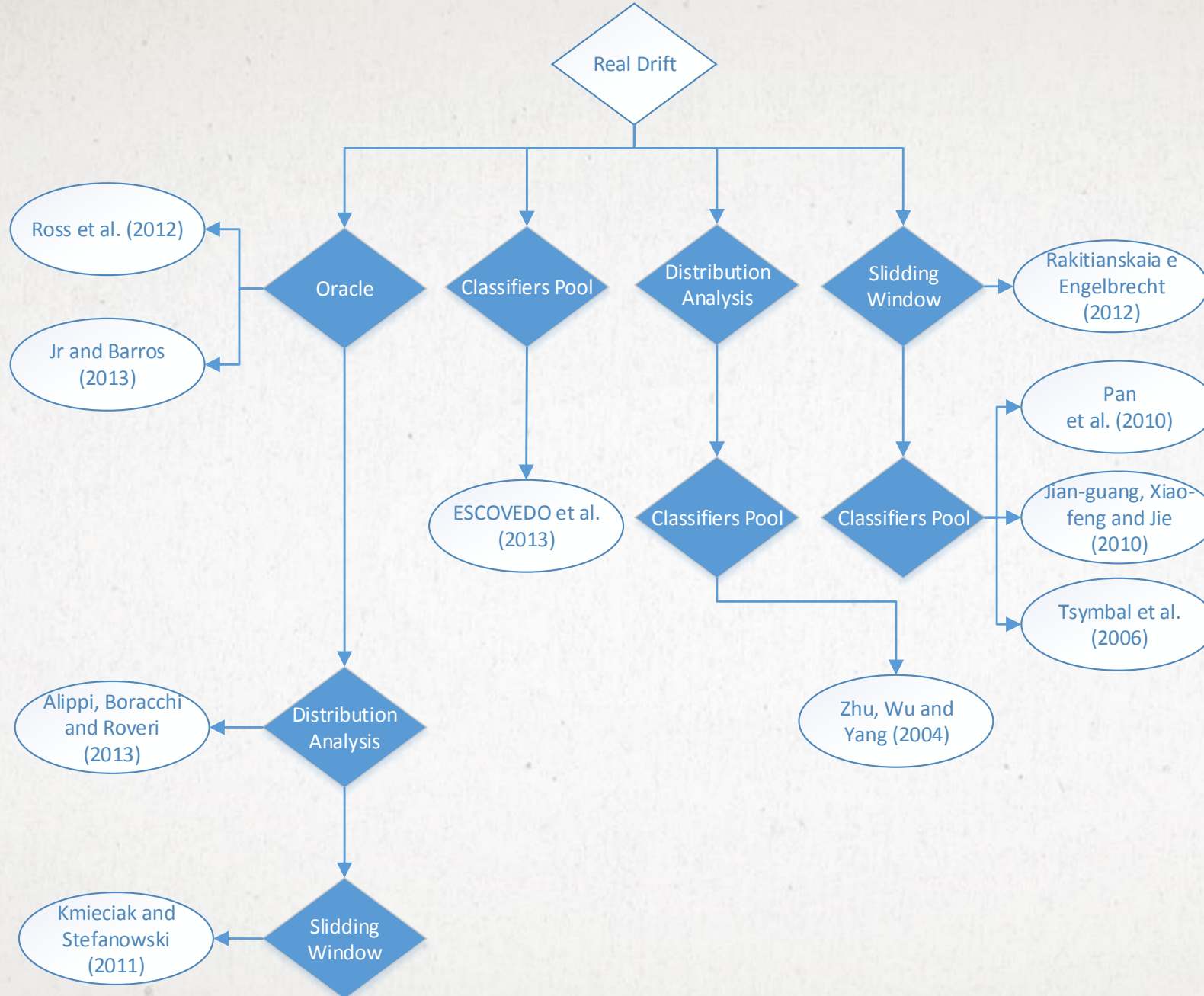


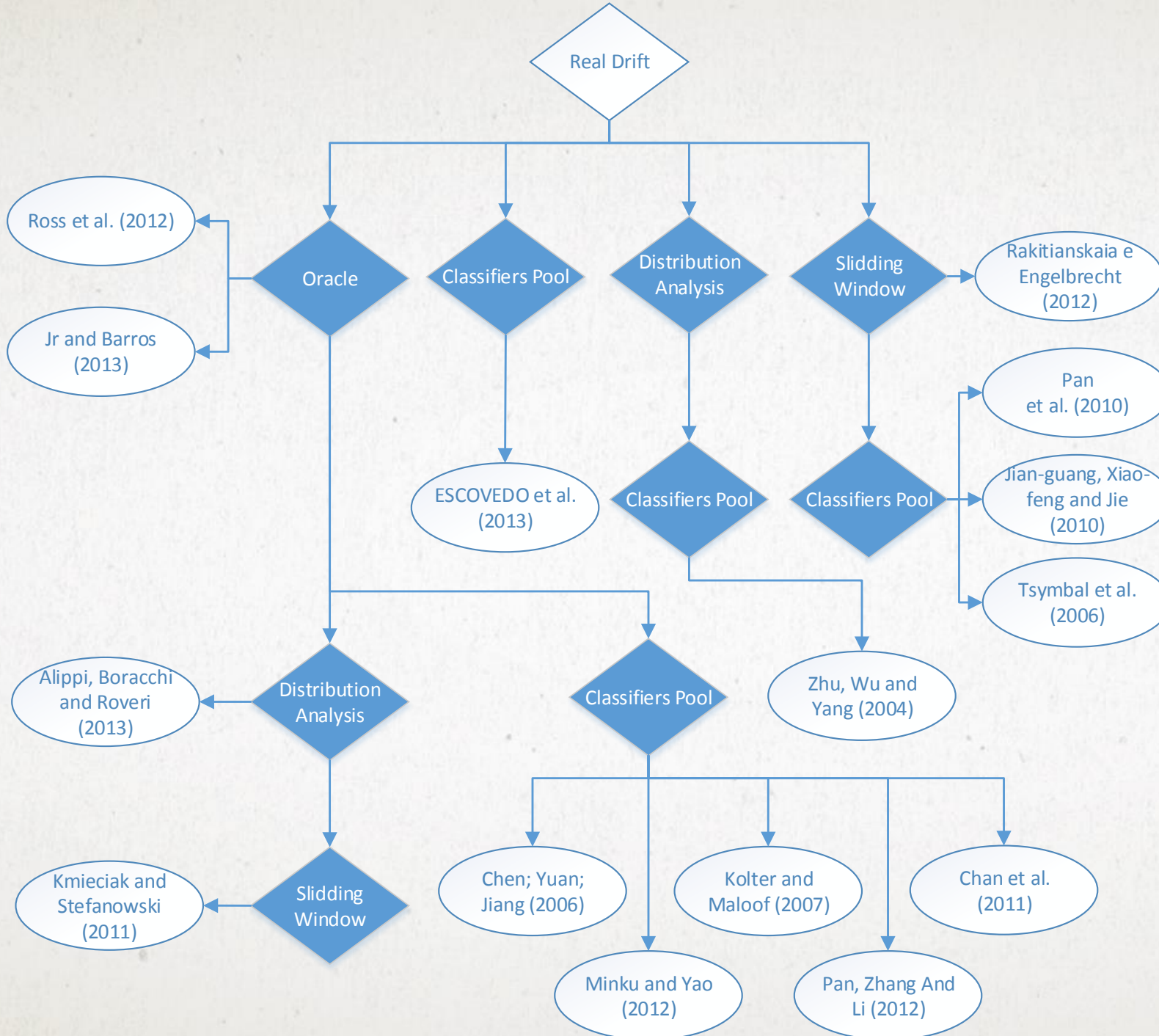




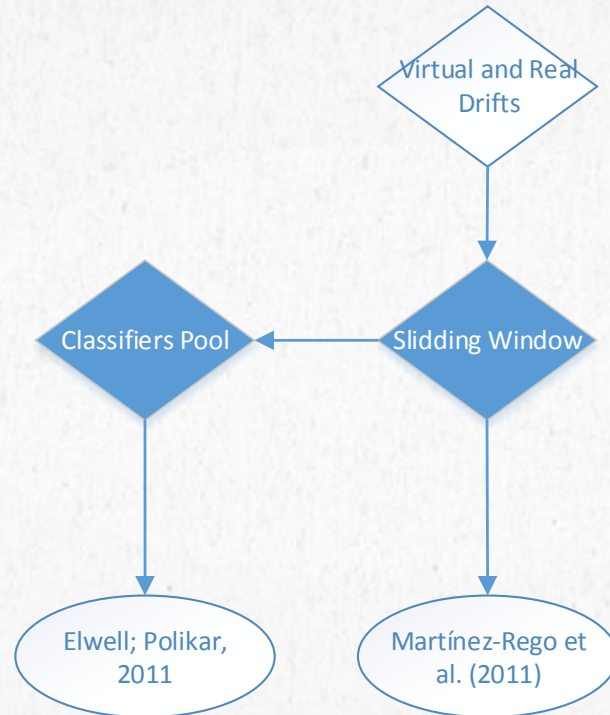












OUR APPROACH

- Use a time window to detect drifts
 - Compute the dissimilarities
 - When a drift happen, the dissimilarities values as expected to change
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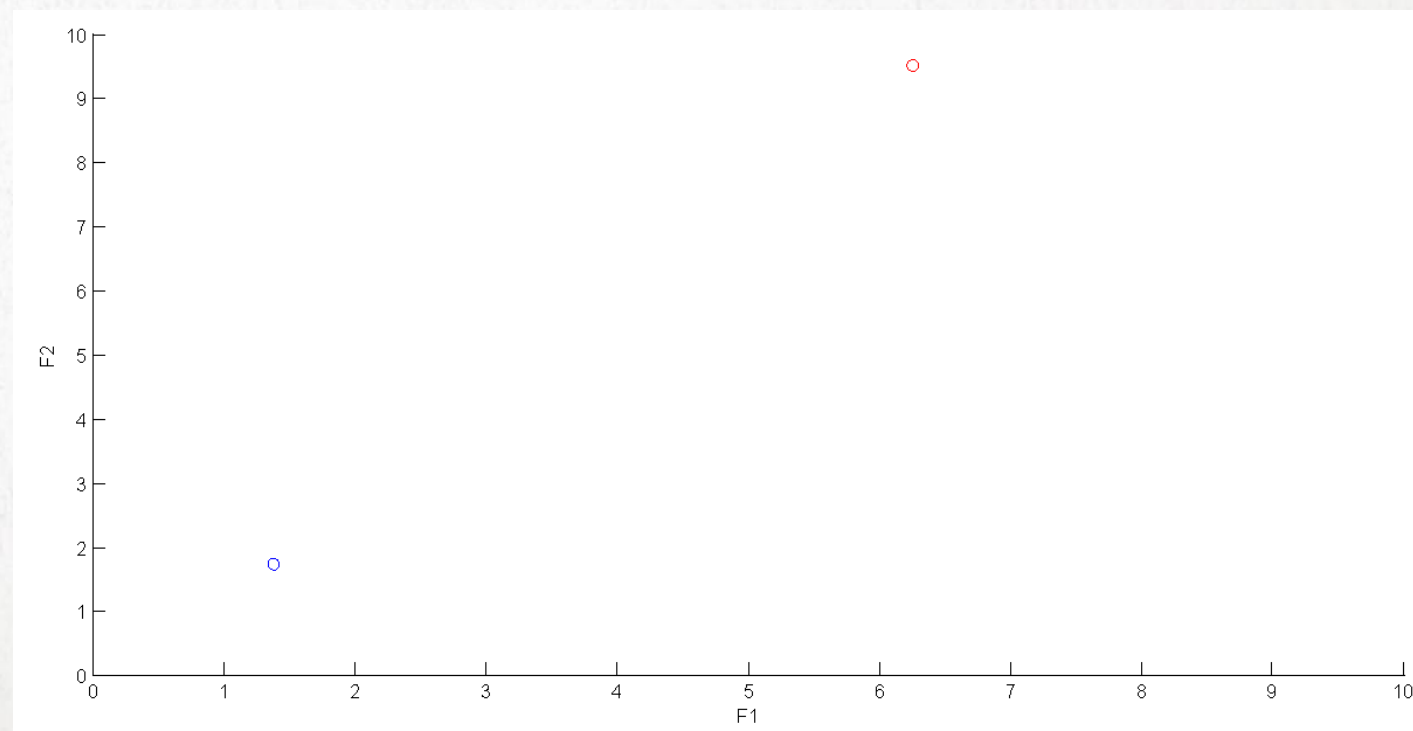
Before the drift

Window

f1	f2	Class
5	12	2
3	12	2
4	13	2
13	5	1
7	13	2
11	5	1
6	12	2
11	1	1
4	12	2
11	1	1

New Supervised Samples

Mean dissimilarity		
	f1	f2
Same class	1.38	1.74
Different classes	6.25	9.5



After the Drift

f1	f2	Class
5	12	2
3	12	2
4	13	2
13	5	1
7	13	2
11	5	1
6	12	2
11	1	1
4	12	2
11	1	1
Window		
4	12	1
4	13	1
14	3	2
12	2	2
3	12	1

New Supervised Samples

New supervised batch arrived with a concept drift

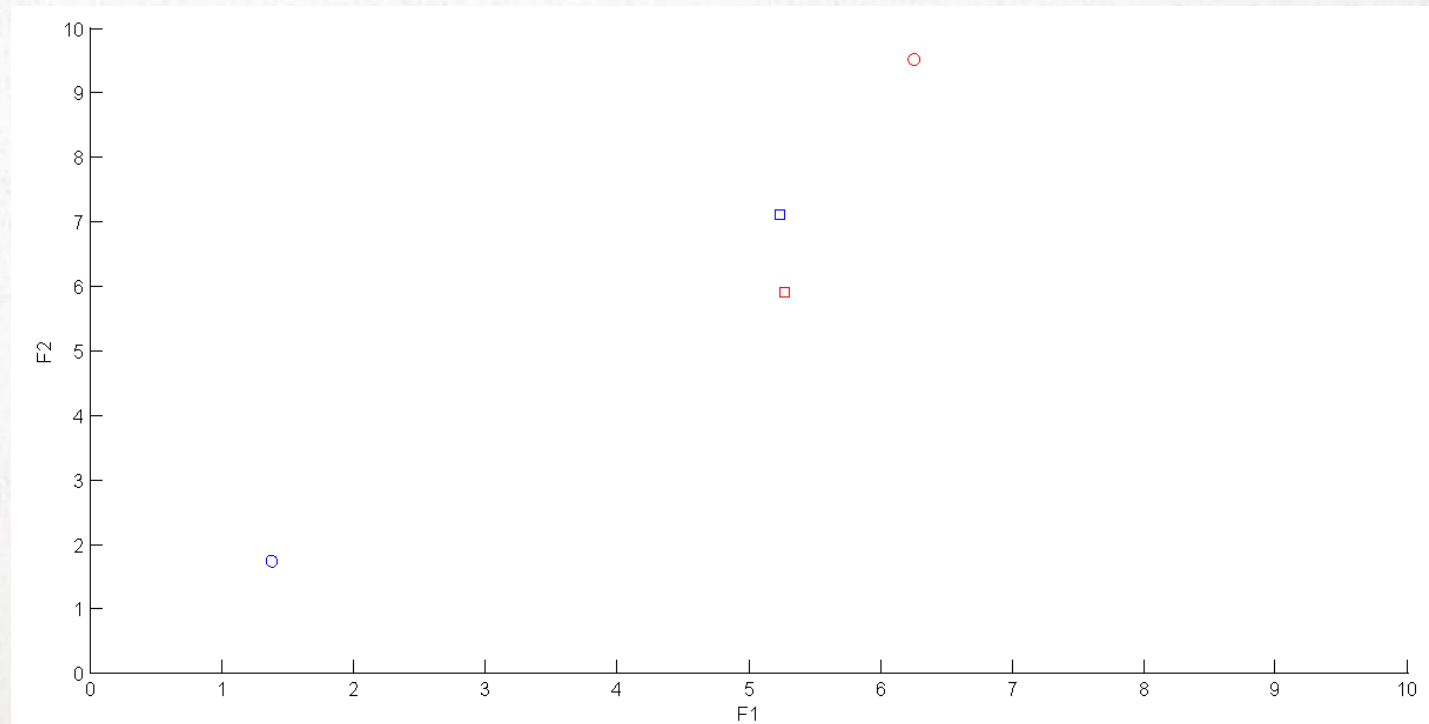
Before the Drift

Mean dissimilarity		
	f1	f2
Same class	1.38	1.74
Different classes	6.25	9.5

After the Drift

Mean dissimilarity		
	f1	f2
Same class	5.23	7.1
Different classes	5.27	5.9

Dissimilarity between same classes increased
Dissimilarity between different classes decreased



QUESTIONS?

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THANKS
